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Cross-walking Three-Axis/Five-Axis Servo Driven Robots

ME WE - 120/ME WE - 120s

注塑用机械手 TAKE-OUT ROBOT

ME WE - 120
ME WE - 120s

STANDARD FUNCTION

256
Packaging motion Max. 256 points

115 × 2
Free packaging motion 115points × 2stage

Forward and rotate at removing side

Posture control during traverse

Posture midway descent at release side

Ejector link

Defective product reject circuit

Initial defective product reject circuit

Delayed arm descent

Midway runner release Move Revert

Runner release within mold

2
Additional vacuum sensing unit 2 circuit

Delayed traverse

Undercut extract circuit

Start signal of conveyor

100
Internal memory for Max 100 molds

Lock function of setting value

Extraction from fixed mold

2
Two language exchange Chinese/English

MODEL

UNIT MEWE - 120 MEWE - 120s

MODEL	UNIT	MEWE - 120	MEWE - 120s
Power Source	V V V	220± 10%	50/60Hz
Max Power Consumption	KWH1	1.9 V	2.8 //V
Air Pressure	Mb	0.5	0.7
		18	
		/AC Servo Motor	
		90°	/90°Fixed
		5	/Incl Chuck Weight
		10.1	
		1200/1400	1200/1400
		---	1250/1450
		M 165 1020	M 400 1020
		1800	
Main Body		450	
		1.6	



• 当机械手为三轴时，尺寸D是1200mm时，尺寸A为1640mmD

• 当机械手为三轴时，尺寸D是1400mm时，尺寸A为140

Feature and scope of the product does not guarantee the product attributes, only for reference. Our scope of delivery and services provided are based solely on the terms of delivery and services provided are based solely on the terms of the contract. Technical data and illustration are only for reference. We reserve the rights of changing.

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